

FS60C/62C UAV hyperspectral measurement system



- Dji M350/300RTK is used as the flight bearing platform.
- Ultra-high speed spectral scanning imaging device with high signal-to-noise ratio provides high stability spectral image acquisition.
- The self-developed image processing algorithm with high efficiency and low power consumption can greatly
 prolong the flight time and reduce the power consumption of the system.
- Through real-time measurement of spectral image information of plants, water bodies, soil and other ground objects, application and precision agriculture, crop growth and yield assessment, forest pest monitoring and fire prevention monitoring, coastline and Marine environment monitoring, lake and watershed environmental monitoring and other applications.
- Compact system design, imaging spectrometer host spectral resolution up to 2.5nm.
- The whole machine consists of: high stability head, hyperspectral imager, embedded data acquisition, processing and storage unit, wireless image transmission system, GPS-RTK navigation system, ground receiving workstation, ground control system, reflectivity calibration board.

Parameter

Hyperspectral camera FS-60C

| Lighting mode | Passive lighting (without light source) | |
|----------------------------|---|--|
| Spectroscopic method | Transmission grating | |
| Spectral range | 400-1000nm | |
| Spectral band | 1200 | |
| Spectral resolution (FWHM) | 2.5 nm | |
| Slit width | 25um | |
| Transmission efficiency | > 60% | |
| Stray light | < 0.5% | |
| Number of spatial pixels | Max. 1920 (software configurable) | |
| Pixel size | 5.86 um | |
| Imaging speed | Full band 128Hz, after ROI can achieve 3300Hz | |
| probe | CMOS | |
| Signal-to-noise ratio | 600/1 | |
| Camera output | USB3.0 or Gigabit network | |
| Camera interface | C-Mount | |
| attachment | USB3.0 or Gigabit network | |
| ROI | Multiple regions | |
| Embedded data acquisition | 5h - dd- d 512666 | |
| Processing storage unit | Embedded processor 512GSSD stora | |
| dimension | 20.5 cmx18.5 cmx12.9 cm | |
| weight | 1200g | |
| Power dissipation | 40W | |
| | | |



- Easy to operate, no need for professional drone operator, can achieve single operation
- The ground station can observe the sampling site of the aircraft in real time and set the preview and correction functions of the route data collected point by point by using the ground station: radiometric correction, reflectivity correction, and area correction support batch processing
- Real-time common vegetation index calculation function
- Support custom real-time analysis model input function
- ENVI is perfectly compatible with multiple data formats

Hyperspectral camera FS-62C

| Spectroscopic method | Transmission grating | | |
|----------------------------|--|----------------------|---|
| Spectral range | 900-1700nm | | |
| Spectral channel number | 1024 | | |
| Spectral resolution (FWHM) | 6.5nm | | |
| Slit width | 25um | | |
| Transmission efficiency | > 60% | | |
| Stray light | < 0.5% | | |
| Number of spatial pixels | 1280 | | |
| Pixel size | 5um | Observation mode | Real-time observation of aircraft sampling sites, hyperspectral images and spectral data by ground stations |
| Imaging speed | Full band 70Hz, maximum 1800Hz | Correction mode | Radiometric correction, reflectivity correction, and area correction support batch processing |
| probe | InGaAs | Data format | Compatible with spe, hdr, and scp formats |
| Signal-to-noise ratio | 600/1 | Camera size | Less than 135*82*100 mm (L * W * H) |
| exportation | start | | (Including lens and built-in embedded data acquisition and processing unit, excluding head) |
| Camera interface | C-Mount | | Less than 190*129*100 mm (L * W * H) |
| attachment | Lens, USB cable, power supply | | (Including lens and built-in embedded data acquisition and processing unit, including head) |
| ROI | Multiple regions | Camera weight | ≤ 740g (including lens and built-in embedded data acquisition and processing unit, excluding PTZ) |
| Built-in processing unit | Windows operating system, 8GB | | ≤ 1085g (including lens and built-in embedded data acquisition and processing unit, including head |
| | of RAM 512GB SSD and camera | attachments | Reflectance calibration board |
| | integrated Design (optional 1TB) | Lens focal length | 25mm |
| Heat dissipation mode | Internal air cooling heat dissipation | Camera scene | > 25° |
| Mode of operation | Easy to operate, no need for prof- essional drone operation Hand co- ntrol, can achieve single operation | Application software | FIGSPEC UAV real-time flight control software, FIGSPEC Merge puzzle software, FIGSPEC Studion image analysis software |
| | | | |



FS-60UC Series UAV hyperspectral measurement system



- Dji M350/300RTK is used as the flight bearing platform.
- Ultra-high speed spectral scanning imaging device with high signal-to-noise ratio provides high stability spectral image acquisition.
- The self-developed image processing algorithm with high efficiency and low power consumption can greatly prolong the flight time and reduce the power consumption of the system.
- Through real-time measurement of spectral image information of plants, water bodies, soil and other ground objects, application and precision agriculture, crop growth and yield assessment, forest pest monitoring and fire prevention monitoring, coastline and Marine environment monitoring, lake and watershed environmental monitoring and other applications.
- Compact system design, imaging spectrometer host spectral resolution up to 2.5nm.
- The whole machine consists of: high stability head, hyperspectral imager, embedded data acquisition, processing and storage unit, wireless image transmission system, GPS-RTK navigation system, ground receiving workstation, ground control system, reflectivity calibration board.

Parameter

| Product model | FS-60UC | | FS-62UC | | FS-64UC | |
|--|--|--|--------------------------------------|------|------------------------------------|--|
| Spectroscopic method | Transmission grating spectroscopy | | | | | |
| Spectral range | 400-1000nm | | 900-1700nm | | 400-1700nm | |
| Spectral band | 1200 | | 1024 | | 250 | |
| Spectral resolution | 2.5nm | | 6.5nm | | 18nm | |
| Slit width | | | 25um | | | |
| Spectral efficiency | >60% | | | | | |
| Stray light | < 0.5% | | | | | |
| Spatial pixel count | 1920 | | 1280 | | 640 | |
| Pixel size | 5.86um*5.86um | | 50 | ım*5 | ōum | |
| Imaging speed | Full band 128Hz | | Full band 70Hz | | Full band 200Hz | |
| Detector | CMOS | | Ir | ıGa | As | |
| SNR(Peak) | | | 600/1 | | | |
| Camera output interface | | USB | | | USB or Gigabit Ethernet | |
| Camera lens interface | | | C-Mount | | | |
| Built-in embedded data acquisition and processing unit | Embedded processor with 512G SSD storage | | | | | |
| Heat dissipation method | 155*95*119mm(L*W*H) | Ir | nternal air cooling heat dissipation | n | 1 | |
| Camera size | ≤840g | | 135*82*100mm(L*W*H) | | 1 | |
| Camera weight | | | ≤740g | | | |
| Accessories | Reflectance calibration panel | | | | | |
| Lens focal length | 25mm | | | | | |
| Lens field of view | >25° | | | | | |
| Flying platform | DJI M350 RTK / M300 RTK | | | | | |
| Aircraft size | In unfolded state, without propellers.:L*W*H 810*670*430 mm In folded state, with propellers.:L*W*H 430*420*430 mm | | | | | |
| Aircraft weight | Empty weight without battery: about 3.77kg. Empty weight with battery: about 6.47kg | | | | | |
| Maximum takeoff weight of aircraft | 9.2kg | | | | | |
| Fastest ascent speed of aircraft | 6m/s | | | | | |
| Fastest horizontal flight speed of aircraft | 23m/s | | | | | |
| Maximum flight time | 55 minutes (measured by flying forward at a speed of about 8 meters per second until the remaining battery level is 0% in a windless environment and under no-load conditions. For reference only. The actual usage time may vary due to different flight modes, accessories and environments) | | | | | |
| Operation mode | It is easy to operate and does no | t require | e a professional drone operator. S | ingl | e-person operation can be achieved | |
| Observation mode | Observe the aircraft sampling location, hyperspectral image and spectral data in real time through the ground station. Function | | | | | |
| Correction method | Radiometric correction, reflectance correction and area correction support batch processing | | | | | |
| Data format | Con | Compatible with spe format, hdr format and scp format. | | | | |
| Application software | FIGSPEC UAV, FIGSPEC Merage mosaic software, and FIGSPEC Studion application software and image analysis software. | | | | | |



Lidar UAV hyperspectral system FS60-UCR



The FS60-UCR series Lidar UAV hyperspectral system is a multifunctional unmanned aerial vehicle detection device that integrates lidar and hyperspectral imaging to obtain lidar and hyperspectral image data.

The main functions include: hyperspectral imaging, with a spectral range of 400-1700nm; a multi-threaded lidar with a ranging distance of up to 300m; an ultra-clear preview camera; a built-in control system in the host; high-precision inertial navigation and solid-state storage. It is suitable for being carried by various drones.

- Spectral range: 400-1700nm
- Spectral resolution: better than 2.5nm
- Spatial pixel count: 1920
- High-precision multi-threaded lidar synchronous measurement

- Ranging distance: 300m.
- Mounted on DJI M350/300 to measure large-area data images.
- Equipped with acquisition and analysis software.

Parameter

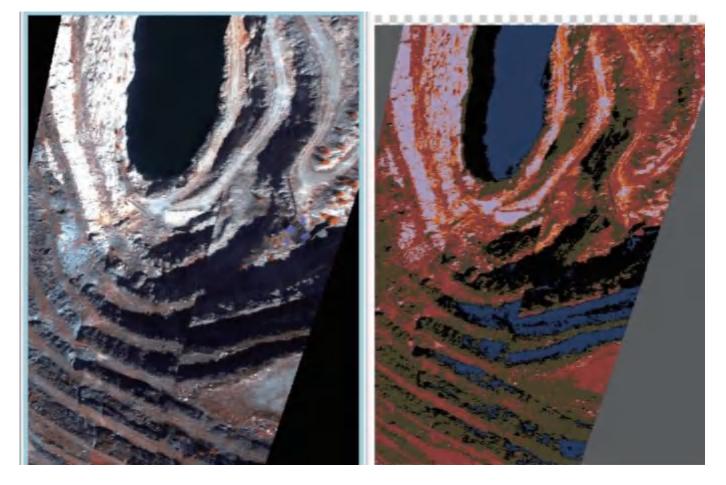
| | | 1 | 1 | | | | |
|--|---|--|---|--|--|--|--|
| Product model | FS-60UCR | FS-62UCR | FS-64UCR | | | | |
| Spectral splitting method | | Transmission grating spectral splittin | g | | | | |
| Spectral range | 400-1000nm | 900-1700nm | 400-1700nm | | | | |
| Spectral bands | 1200 | 1024 | 250 | | | | |
| Spectral resolution | 2.5nm | 6.5nm | 18nm | | | | |
| Slit width | | 25um | | | | | |
| Spectral efficiency | >60% | | | | | | |
| Stray light | | < 0.5% | | | | | |
| Spatial pixel count | 1920 | 1280 | 640 | | | | |
| Pixel size | 5.86um*5.86um | 5u | m*5um | | | | |
| Imaging speed | Full band 128Hz | Full band 70Hz | Full band 200Hz | | | | |
| Detector | CMOS | lr Ir | nGaAs | | | | |
| SNR (Peak) | | 600/1 | | | | | |
| Camera output interface | US | SB | USB or Gigabit Ethernet | | | | |
| Camera lens interface | | C-Mount | | | | | |
| Built-in embedded data acquisition and processing unit | Embedded processor with 512GB SSD storage | | | | | | |
| Heat dissipation method | | Internal air cooling | | | | | |
| Spectral camera size | 155*95*119mm(L*W*H) | 135*82*100mm(L*W*H) | / | | | | |
| Accessories | Reflectance calibration plate | | | | | | |
| Focal length of spectral camera lens | 25mm | | | | | | |
| Field of view of spectral camera lens | >25° | | | | | | |
| Measurement accuracy of lidar system | 5cm | | | | | | |
| Lidar ranging distance | 300m | | | | | | |
| Lidar scanning field of view angle | 40.3° (vertical) * 360° (horizontal) | | | | | | |
| Lidar point frequency | 640,000 points/second (single echo) 1,280,000 points/second (double echo) 1,920,000 points/second (triple echo) | | | | | | |
| Lidar built-in camera pixel | 26 million (6252*4168) | | | | | | |
| Lidar lens focal length | 16mm | | | | | | |
| Flight platform | DJI M350 RTK / M300 RTK. | | | | | | |
| Aircraft size | Unfolded state, without blades: length * width * height 810*670*430 mm Folded state, with blades: length * width * height 430*420*430 mm | | | | | | |
| Aircraft weight | Empty aircraft without b | oattery: about 3.77 kg. Empty aircraft v | vith battery: about 6.47 kg | | | | |
| Maximum takeoff weight of aircraft | 9.2kg | | | | | | |
| Fastest ascent speed of aircraft | 6m/s | | | | | | |
| Maximum horizontal flight speed of aircraft | 23m/s | | | | | | |
| Longest flight time | 55 minutes (measured in a windless environment and under no-load conditions by flying forward at a speed of approximately 8 meters per second until the remaining battery power is 0%. For reference only. The actual usage time may vary due to different flight methods, accessories, and environments) | | | | | | |
| Operation mode | Easy to operate. No profession | nal drone operator is required. Single- | person operation can be realized | | | | |
| Observation mode | Real-time observation of the aircraft sampling location, hyperspectral image, and spectral data through the ground station. Function | | | | | | |
| Correction mode | Radiance correction, reflectance correction, and area correction support batch processing | | | | | | |
| Data format | Compatible with spe format, hdr format, and scp format | | | | | | |
| Application software F | FIGSPEC UAV, FIGSPEC Merage mo | saic software, FIGSPEC Studion appli | ication software, image analysis software | | | | |

Airborne Hyperspectral Camera Mining Test

The UAV hyperspectral imaging system can quickly collect high-resolution images of the surface by carrying a hyperspectral sensor, capturing the spectral characteristics of different minerals. This enables explorers to quickly identify potential ores and mineralized zones, greatly improving exploration efficiency.



After analyzing the collected data, we get the above group of pictures under different bands.

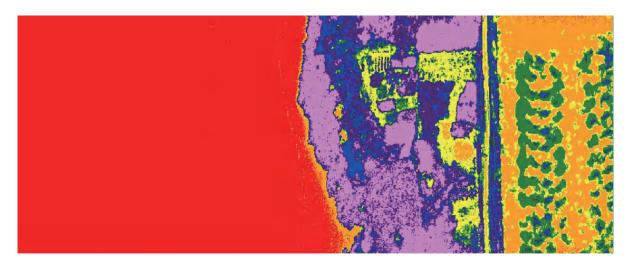


The above unsupervised clustering algorithm image is obtained through analysis software

Use Airborne Hyperspectral Camera to Photograph Ponds to Obtain NDVI Images and Images of Potassium Permanganate Distribution in the Water



Raw image



NDVI image

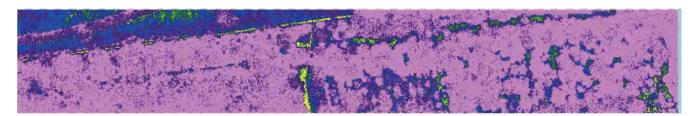


Potassium permanganate distribution image

NDVI Image Analysis and Supervised Clustering after Photographing the Forest Using Airborne Hyperspectral Camera



Raw image



NDVI image



Supervision Cluster image

Accessories Introduction

| Accessories Description | Quantity | Accessories Description | Quantity |
|---|----------|---|----------|
| Host | 1 | Adapter 12V 3A | 1 |
| HDMI high-definition cable 0.5m | 1 | Standard lens | 1 |
| USB flash drive | 1 | Certificate of Conformity & Warranty Card | 1 |
| Packing List | 1 | Ziplock Bags | 1 |
| Black aluminum alloy box | 1 | Outer packaging carton | 1 |
| "This side is facing up, please do not turn it upside down; please do not drop this precision instrument." | 1 | | |